Autolab

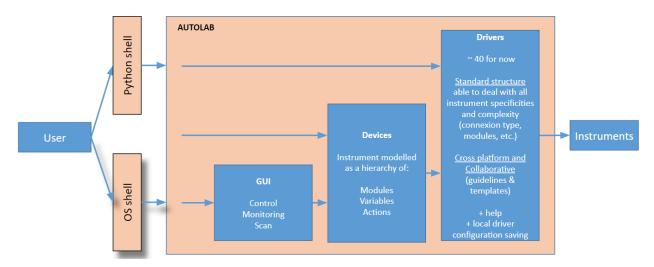
Feb 21, 2020

Contents

1	Installation	5
2	Drivers (Low-level interface)	7
3	Devices (High-level interface)	21
4	Local configuration	25
5	Graphical User Interface (GUI)	29
6	OS shell	37
7	Doc / Reports / Stats	43
8	Releases notes	45
9	About	47

"Forget your instruments, focus on your experiment!"

Autolab is a Python package dedicated to control remotely any laboratory instruments and automate scientific experiments in the most user-friendly way. This package provides a set of standardized drivers for about 40 instruments (for now) which are ready to use, and is open to inputs from the community (new drivers or upgrades of existing ones). The configuration required to communicate with a given instrument (connection type, address, ...) can be saved locally to avoid providing it each time. Autolab can also be used either through a Python shell, an OS shell, or a graphical interface.



In this package, the interaction with a scientific instrument can be done through two different objects : the **Drivers**, or the **Devices**.

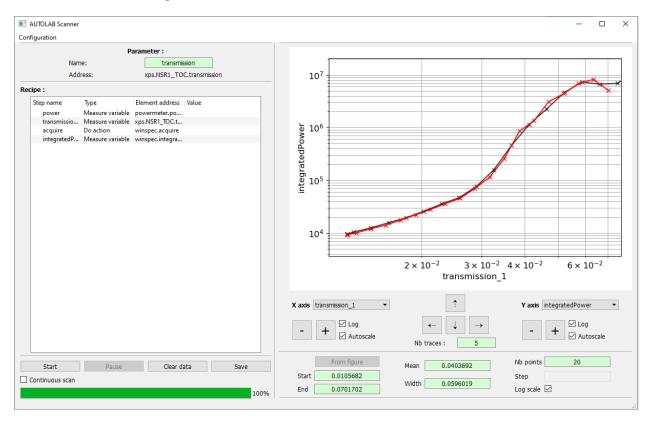
• The Drivers (Low-level interface) provides a raw access to the package's drivers functions.

• The *Devices (High-level interface)*, are an abstraction layer of the low-level interface that provide a simple and straightforward way to communicate with an instrument, through a hierarchy of Modules, Variables and Actions objects.

```
(continued from previous page)
```

```
>>> laserSource.wavelength()
                                                          # Read the Variable
→ 'wavelength'
1550
>>> powerMeter = autolab.get_device('my_powermeter')
                                                          # Create the Device
→ 'my_powermeter'
>>> powerMeter.power()
                                                          # Read the Variable
→ 'power'
156.89e-6
>>> stage = autolab.get_device('my_stage')
                                                          # Create the Device
→ 'my_stage'
>>> stage.home()
                                                          # Execute the Action
→ 'home'
```

The user can also interact even more easily with this high-level interface through a user-friendly *Graphical User Interface (GUI)* which contains three panels: A Control Panel (graphical equivalent of the high-level interface), a Monitor (to monitor the value of a Variable in time) and a Scanner (to scan a Parameter and execute a custom Recipe).



All the Autolab's features are also available through an os_shell interface (Windows and Linux) that can be used to perform for instance a quick single-shot operation without opening explicitly a Python shell.

>>> autolab devices my_tunics.wavelength -v 1551

Note: A Google Slides presentation and examples are available here: bit.ly/autolab-demo

Table of contents:

CHAPTER 1

Installation

1.1 Python

This package is working on Python version 3.6+.

- On Windows, we recommend to install Python through the distribution Anaconda: https://www.anaconda.com/
- On older versions of Windows (before Windows 7), we recommend to install Python manually: https://www.python.org/
- On Linux, we recommend to install Python through the apt-get command.

Additional required packages (installed automatically with Autolab):

- numpy
- pandas
- pyvisa
- python-vxi11

1.2 Autolab package

This project is hosted in the global python repository PyPi at the following address : https://pypi.org/project/autolab/ To install the Autolab python package on your computer, we then advice you to use the Python package manager pip in a Python environmement:

pip install autolab

If the package is already installed, you can check the current version installed and upgrade it to the last official version with the following commands:

```
pip show autolab
pip install autolab --upgrade
```

Import the Autolab package in a Python shell to check that the installation is correct.

>>> import autolab

1.3 PyQt5 for the GUI

The GUI requires the package PyQt5. But depending if you are using Anaconda or not, the installation is different:

With Anaconda:

conda install pyqt

Without:

pip install pyqt5

1.4 Development version

You can install the latest development version (at your own risk) directly form GitHub:

pip install http://github.com/qcha41/autolab/zipball/master

CHAPTER 2

Drivers (Low-level interface)

In Autolab, a **Driver** refers to a Python class dedicated to communicate with one particular instrument. This class contains functions that perform particular operations, and may also contain subclasses in case some modules or channels are present in the instrument. Autolab comes with a set of about 40 different **Drivers**, which are ready to use.

The first part of this section explains how to configure and open a **Driver**, and how to use it to communicate with your instrument. The, we present the guidelines to follow for the creation of new driver files, to contribute to the Autolab Python package.

Table of contents:

2.1 Load and use a Driver

The low-level interface provides a raw access to the drivers implemented in Autolab, through a **Driver** object, which contains functions that perform particular operations in your instrument.

Attention: The Autolab drivers may contains internal functions, that are not dedicated to be called by the user, and some functions requires particular types of inputs. The authors declines any responsibility for the consequences of an incorrect use of the drivers. To avoid any problems, make sure you have a real understanding of what you are doing, or prefer the use of the *Devices (High-level interface)*.

To see the list of available drivers in Autolab, call the list_drivers function.

```
>>> import autolab
>>> autolab.list_drivers()
```

Note: The driver of your instrument is missing ? Please contribute to Autolab by creating yourself a new driver, following the provided guidelines : *Write your own Driver*

2.1.1 Load and close a Driver

The instantiation of a *Driver* object is done through the function get_driver of Autolab, and requires a particular configuration:

- The name of the driver: one of the name appearing in the list_drivers function (ex: 'yenista_TUNICS').
- The connection parameters as keywords arguments: the connection type to use to communicate with the instrument ('VISA', 'TELNET', ...), the address, the port, the slots, ...

```
>>> laserSource = autolab.get_driver('yenista_TUNICS', 'VISA', address='GPIB0::12::INSTR
__')
```

To know what is the required configuration to interact with a given instrument, call the function config_help with the name of the driver.

>>> autolab.config_help('yenista_TUNICS')

To avoid having to provide each time the full configuration of an instrument to load a **Driver** (as above), Autolab proposes to store locally this configuration. To learn more about this, please see the section local_config. You can then just provide the configuration name in the function get_driver.

>>> laserSource = autolab.get_driver('my_tunics')

Note: You can overwrite temporarily some of the parameters values of a configuration by simply providing them as keywords arguments in the get_driver function:

To close properly the connection to the instrument, simply call its the function close of the **Driver**.

```
>>> lightSource.close()
```

2.1.2 Use a Driver

You are now ready to use the functions implemented in the Driver:

```
>>> laserSource.set_wavelength(1550)
>>> laserSource.get_wavelength()
1550
```

You can get the list of the available functions by calling the function autolab.explore_driver with the instance of your **Driver**. Once again, note that some of these functions are note supposed to be used directly, some of them may be internal functions.

```
>>> autolab.explore_driver(laserSource)
```

2.1.3 Script example

With all these commands, you can now create your own Python script. Here is an example of a script that sweep the wavelength of a light source, and measure a power of a power meter:

```
# Import the package
import autolab
import pandas as pd
# Open the Devices
myTunics = autolab.get_driver('my_tunics')
myPowerMeter = autolab.get_driver('my_power_meter')
# Turn on the light source
myTunics.set_output(True)
# Sweep its wavelength and measure a power with a power meter
df = pd.DataFrame()
for wl in range(1550,1560,0.01) :
    # Set the parameter
   myTunics.set_wavelength(wl)
    # Measures the values
   wl_measured = myTunics.get_wavelength()
   power = myPowerMeter.line1.set_power()
    # Store the values in a list
   df = df.append({'wl_measured':wl_measured, 'power':power},ignore_index=True)
# Turn off the light source
myTunics.set_output (False)
# Close the Devices
myTunics.close()
myPowerMeter.close()
# Save data
df.to_csv('data.csv')
```

2.2 Write your own Driver

The goal of this tutorial is to present the general structure of the drivers of this package, in order for you to create simply your own drivers, and make them available to the community within this collaborative project. We notably provide a fairly understandable driver structure that can handle the highest degree of instruments complexity (including: single and multi-channels function generators, oscilloscopes, Electrical/Optical frames with associated interchangeable submodules, etc.). This provides reliable ways to add other types of connection to your driver (e.g. GPIB to Ethenet) or other functions (e.g. get_amplitude, set_frequency, etc.).

Note: To help you with writting your own drivers a few templates are provided on the GitHub page of the project.

We will first discuss the generalities to create a new driver or modify an existing one and share it with the community in **getting started: create a new driver**, that will particularly describe the required convention (location, files and namings) as well as the actual way to share it with the community (addition to the main package), and finally we will detail the typical **driver structure** as well as the required homogeneities. Those last will ensure that all the features of the drivers you would add are best used by autolab's utilities (helps, gui, parser, etc.).

2.2.1 Getting started: create a new driver

To develop your own drivers, autolab provide you with a directory named local_drivers (located at ~/auto-lab/local_drivers, where ~ represents the user root) created when the package is installed. This directory is inspected by autolab to search for locally defined drivers. This way you may modify existing drivers (addition of new functions, etc.) or create new drivers to drive new instruments not yet supported by autolab.

Note: Each driver name should be unique: do not define new drivers (in your local folders) with a name that already exists in the main package.

In the local_drivers directory, as in the main package, each instrument has/should have its own directory organized and named as follow. The name of this folder take the form *<manufacturer>_<MODEL>*. The driver associated to this instrument is a python script taking the same name as the folder: *<manufacturer>_<MODEL>*.py. A second python script, allowing the parser to work properly, should be named *<manufacturer>_<MODEL>_utilities.py* (find a minimal template here). Additional python scripts may be present in this folder (devices's modules, etc.). Please see the existing drivers of the autolab package for extensive examples.

For addition to the main package: Once you tested your driver and it is ready to be used by others, you can send the appropriate directory to the contacts (*About*).

Warning: General note

• The imports of additional modules (numpy, pandas, time, etc.) should be made in the class they are needed so that the imports are done only if needed (e.g. import visa within the Driver_VISA class).

2.2.2 Driver structure (<manufacturer>_<MODEL>.py file)

The Driver is organized in several python class with a structure as follow. The numbers represent the way sections appear from the top to the bottom of an actual driver file. We chose to present the sections in a different way:

1 - import modules (optionnal)

To import possible additional modules, e.g.:

```
import time
from numpy import zeros, ones, linspace
```

3 - class Driver_CONNECTION

The class Driver_CONNECTION: establish the connection with the instrument and define the communication functions.

As a reminder, a communication with an instruments occurs in general with strings that are set by the manufacturer and instrument and model dependent. To receive and send strings from and to the instrument we first need to establish a connection. This will be done using dedicated python package such as *pyvisa*, *pyserial*, *socket* and physical connections such as Ethernet, GPIB, or USB. See bellow for an example help with using a VISA type of connection.

```
Caution: The connection types are refered to with capital characters in the classes names, e.g.:

class Driver_SOCKET():

class Driver_TELNET():
```

When using the driver module (.py) the Driver_CONNECTION class is imported as the top layer, it inherits all the attributes of the Driver class and run its <u>__init__</u> function. It is the class that is used. Note that the connection classes are located, within a driver module, bellow the Driver class, because they use it before reaching their own <u>__init__</u> function.

Here is a commented example of the Driver_CONNECTION class, further explained bellow:

```
*******
→####
→ # # # #
class Driver_VISA (Driver):
                             # Inherits all the attributes of the
→class Driver
  def __init__(self, address='GPIB0::2::INSTR',**kwargs): # 0) Definition_
→of the ``__init__`` function
      import visa
                             # 1) Connection library to use
      rm = visa.ResourceManager() # Use of visa's ressource manager
      self.inst = rm.get_instrument(address) # 2) Establish the_
↔ communication with the instrument
      Driver.__init__(self)
                            # 3) Run what is define in the Driver.___
⇔init__ function
   # Communication functions
  def write(self,command):
                            # 4) Defines a write function
     self.inst.write(command)
ument
                            # Sends a string 'command' to the
⇔instrument
  def read(self):
                            # 5) Defines a read function
     rep = self.inst.read()
                            # Receives a string 'rep' from the
⇔instrument and return it
     return rep
  def query(self,query):
                            # 6) Defines a query function: combine_
\rightarrowyour own write and read functions to send a string and ask for an answer
     self.write(query)
      return self.read()
   def close(self):
                             # 7) Closes the communication
      self.inst.close()
→ # # # #
*************
→ # # # #
```

In this case the Driver_CONNECTION class is called Driver_VISA. To use a driver we usually create an instance of the Driver_CONNECTION class (cf. *Load and use a Driver*):

This execute the __init__ function that (following this example labels): 1) import the connection type library

2) load the instrument (using its address and eventual other arguments)

3) run the Driver.__init__ (for everything not related with the connection to the instrument, detailed in the Driver class section)

In general, the <u>__init__</u> function should establish the connection and store the instrument Instance in a class attribute (here: self.inst). (The communication functions that follow will use this attribute.)

Importantly, the communication functions are (re-)defined in this class including write [4)], read [5)], query [6)] and close [7)] functions that are the bare minimum. They are the ones that must be used in all the other classes (Driver, Module_, etc.). They must take **a string as argument** and **return a string, without any termination character** (e.g. n, r, etc.). This way several connection classes can coexist and use the same other classes allowing different possible physical connections and in general more flexibility.

Caution: Several points are worth noting:

- 0) The __init__ function definition should explicitely contain all the arguments that are necessary to establish the communication (in this exemple address) along with a default value (for example the one that works for you), in order for the automatic autolab help to behave properly. The __init__ function definition should also have an extra argument **kwargs allowing to accept and possibly pass any extra argument provided.
- 3) For more complicated instruments an additional argument **kwargs would be provided, giving:

```
Driver.___init___(self,**kwargs)
```

This enables passing extra arguments (e.g. slot configuration, etc.) to the Driver class, that will instantiate the instrument configuration, in the form of a dictionnary.

• 7) The close function is mandatory, even though you do not use it in any of the other classes of the *<manufacturer>_<MODEL>.py* file.

Further instrument complexity:

With further instrument and/or connection type complexity you will need to add other arguments to the <u>___init__</u> function of Driver_CONNECTION class. As an example to add an argument board_index for a GPIB connection type, you would need to modify the example line 0) to:

```
def __init__ (self, address=19, board_index=0, **kwargs):
```

You may also need to pass arguments to the class Driver (see next section), that may come from e.g. the number of channels of an oscilloscope or the consideration of an instrument with *slots*, you would need to modify line 3) of the example:

```
Driver.___init___(self,**kwargs)
```

Please check out autolab existing drivers for more examples and/or to re-use existing connection classes (those would most likely need small adjustments to fit your instruments).

Note: Help for VISA addresses

For *visa* module to work properly, you need to provide an address for communication, that you may be able to get types the few next lines:

```
import visa
rm = visa.ResourceManager()
rm.list_resources()
```

Just execute them before and after plugging in your instrument to see which address appears. For ethernet connections, you should know the IP address (set it to be part of your local network) and the port (instrument documentation) of your instrument.

Examples of visa addresses may be find here online :

```
TCPIP::192.168.0.5::INSTR
GPIB0::3::INSTR
```

2 - class Driver

The class Driver: **establish the connection with internal modules or channels** (optionnal as dependant on the instrument, see next section) and **define instrument-related functions**.

After the communication with your instrument is established, we need to send commands or receive answers (to get the results of a query or a requested command). The communication part being manage by the class Driver_CONNECTION, any time we want to send a (instrument-specific) command to the instrument from the class Driver, we need to use the communication functions defined in the class Driver_CONNECTION.

The class Driver_CONNECTION inherits all the attributes of the class Driver. The function ___init___ of the class Driver is run by the class Driver_CONNECTION. The Driver class will act as your main instrument.

Here is a commented example of the class Driver, further explained bellow:

```
class Driver():
   def __init__(self):
                                            # 1) Definition of the ``___init__
  `` function
       import time
                                            # 2) Additional imports and/or
→ setup additional attributes
       self.write('VUNIT MV')
                                            # 3) Run additional commands to
\leftrightarrowinstantiate the instrument (e.g. set the vertical unit to be used)
   def set_amplitude(self,amplitude):
                                           # 4) Defines a function to set a
→ value to the instrument
       self.write(f'VOLT {amplitude}') # 5) Sets the amplitude,...
→instrument specific
   def get_amplitude(self):
                                            # 6) Defines a function to query_
\hookrightarrowa value to the instrument
       return float (self.query (f'VOLT?')) # 7) Returns the amplitude,
⇔instrument specific
   def single_burst(self):
                                            # 8) Defines a function to,
→perform an action
       self.write('BRST SINGLE')
                                            # 9) Triggers a single burst,
⇔instrument specific
   def idn(self):
                                            # 10) This function should work
→with all instruments
       self.write('*IDN?')
                                            # 11) '*IDN?' should be
→understood by all instruments
                                                                 (continues on next page)
```

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```
return self.read()
⇔of an instrument
```

12) Returns the identification.

When the class Driver_CONNECTION is is instantiated, the __init__ function is executed. It does the following (follow 1) import additional libraries

2) run additional commands to instantiate the instrument (e.g. set the vertical unit to be used)

Caution: For further instrument complexity, including multi-channels instruments (generators, oscilloscopes, etc.) or instruments with *slots*, the instantiation of additional classes must be done here. See the following examples.

needs to be done then, one can just:

```
def __init__(self,nb_channels=2):
                                          # 1)
   pass
```

Importantly, the class Driver defines all the functions that are related to the main instrument: to set [4)]/query [6)] some values (e.g. the output amplitude of a function generator) or perform actions (e.g. trigger a single burst event).

Caution: Several points are worth noting:

- 1) Favor python f strings (f') that are more, especially when an argument has to be passed to the function, that are more robust to different types [5)].
- 2) You should explicitly convert the string returned by Driver_CONNEXION.query() (or Driver_CONNEXION.read) to the expected variable type [7)].
- 3) For more complex instruments (i.e. with additional classes), please refer to the next section. In general, only the functions associated with the **main** instrument should be found here.

Further instrument complexity:

Here is a way to modify the ______ function of the class Driver to deal with the case of a **multi-channel instrument**. (Note: some of the lines have been removed from the previous example for clarity.) It is further explained bellow:

```
def __init__(self,nb_channels=2):
                                          # 1) Definition of the ``
→init__`` function
    self.nb_channels = int(nb_channels) # 2) Set arguments given to...
→the class as class attributes to be re-used elsewhere (within the...
\hookrightarrow class)
    for i in range(1,self.nb_channels+1):
        setattr(self,f'channel{i}',Channel(self,i)) # 3) Set_
→additional Module\_MODEL classes (called Channel here) as classes
→attibutes
```

Here, the number of channels is provided as argument to the __init__ function [1)], and for each channel [3] an attribute of the class Driver is created by instantiating an additional class called **Channel**. The line 3) is formally equivalent to (considering: i=1):

```
self.channel1 = Channel(self,1)
```

All the channels are thus equivalent in this example as they use the same additional class (**Channel**). The arguments provided to the class **Channel** are: all the attributes of the actual class (**Driver**) and the number of the instantiated channel; both will be used in the additional class (e.g. the connection functions, etc.)

The previous structure should be used only if the physical slot configuration is naturally fixed by the manufacturer (a power meter with two channels for instance). In the particular case of an **instrument with 'slots'**, all the *channels* are not equivalent. They rely on different physical modules that may be disposed differently and in different numbers for different users. Then one class for each different module (that are inserted in a main frame) should be defined (**Module_MODEL**). Here is a way to modify the <u>__init__</u> function of the class Driver to deal with the case of an instrument with *slots*:

This will parse the arguments received by the <u>__init__</u> function (of the class **Driver**) in the **kwargs appropriately to instantiate the right combination Modules/Slots providing the Modules (additional classes) follow some naming conventions (explained in the next section).

Note: For the particular case of instruments that one usually gets 1 dimensionnal traces from (e.g. oscilloscope, spectrum annalyser, etc.), it is useful to add to the class Driver some user utilities such as procedure for channel acquisitions:

```
### User utilities
def get_data_channels(self, channels=[], single=False):
    """Get all channels or the ones specified"""
   previous_trigger_state = self.get_previous_trigger_state()
              # 1)
    self.stop()
              # 2)
    if single: self.single()
              # 3)
    while not self.is_stopped(): time.sleep(0.05)
              # 4)
 \rightarrow 
   if channels == []: channels = list(range(1, self.nb_channels+1))
    for i in channels:
        if not(getattr(self,f'channel{i}').is_active()): continue
        getattr(self,f'channel{i}').get_data_raw()
               # 5)
        getattr(self,f'channel{i}').get_log_data()
              # 6)
_
    self.set_previous_trigger_state(previous_trigger_state)
              # 7)
_
def save_data_channels(self,filename,channels=[],FORCE=False):
   if channels == []: channels = list(range(1, self.nb_channels+1))
    for i in channels:
        getattr(self,f'channel{i}').save_data_raw(filename=filename,
\rightarrow FORCE=FORCE) # 8)
        getattr(self,f'channel{i}').save_log_data(filename=filename,
→FORCE=FORCE) # 9)
```

These functions rely on some other functions that should be implemented by the user (single, get_previous_trigger_state, etc.). The reader may find a find a full template example here.

Overall, the function get_data_channels:

- 1) Store the previous trigger state
- 2) Stop the instrument
- 3) Trigger a single trigger event (if requested)
- 4) Wait for the scope to be stopped
- 5) Acquire the channels provided (all if no channel is provided)
- 6) Acquire the logs of the channels provided (all if no channel is provided)
- 7) Set the previous trigger state back

Overall, the function save_data_channels:

- 8) Save the channels provided (all if no channel is provided)
- 9) Save the logs of the channels provided (all if no channel is provided)

4 - Additional class (optionnal)

Caution: Additional classes namings

The additional classes should be named **Module_MODEL**. Exceptions do occur for some oscilloscopes (**Channel**), spectrum annalyser (**Trace**) or some multi-channel instruments (**Output**), in which case we stick to the way it is referred to as in the Programmer Manual of the associated instrument.

In the particular case of an **instrument with 'slots'**, all the *channels* are not equivalent. They rely on different physical modules that may be disposed differently and in different numbers for different users. Then one class for each different module (that are inserted in a main frame) should be defined (**Module_MODEL**). The ___init___ function of the class **Driver** will deal with which class **Module_MODEL** to instantiate with which *slot* depending on the actual configuration of the user. Thus the class **Module_MODEL** (or **Channel**, etc.) have all a similar structure, structure that is similar to the one of the class Driver. In other words the class **Driver** deal with the *main* instruments while the additional classes deal with the sub-modules.

Here is an example of the class Channel of a double channel function generator:

```
class Channel():
    def __init__(self,dev,channel):
        self.channel = int(channel)
        self.dev = dev
    def amplitude(self,amplitude):
        self.dev.write(f':VOLT{self.channel} {amplitude}')
    def offset(self,offset):
        self.dev.write(f':VOLT{self.channel}:OFFS {offset}')
    def frequency(self,frequency):
        self.dev.write(f':FREQ{self.channel} {frequency}')
```

Here is an example of the two class Module_MODEL of a instrument with *slot* for which slots are non-equivalent (strings needed to perform the same actions are different):

```
class Module_TEST111() :
    def __init__(self,driver,slot):
        self.driver = driver
```

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```
self.slot = slot
def set_power(self,value):
    self.dev.write(f'POWER={value}')
def get_power(self):
    return float(self.dev.query('POWER?'))
class Module_TEST222() :
    def __init__(self,driver,slot):
        self.driver = driver
        self.driver = driver
        self.slot = slot
def set_power(self,value):
        self.dev.write(f'POWER={value}')
    def get_power(self):
        return float(self.dev.query('POWER?'))
```

One can note (for both cases):

- 2) The connection functions used are the one coming from the class **Driver**, thus one now call them self.dev.connection_function (for connection_function defined in the class **Driver_CONNECTION** in: write, read, query, etc.).
- 3) Finally there is a collection of functions that are *channel/slot*-dependant.

Note: For the particular case of instruments that one usually gets 1 dimensionnal traces from (e.g. oscilloscope, spectrum annalyser, etc.), it is useful to define functions to get and save the data. See the folliwing instrument dependant example:

```
def get_data_raw(self):
    if self.autoscale:
        self.do_autoscale()
    self.dev.write(f'C{self.channel}:WF? DAT1')
    self.data_raw = self.dev.read_raw()
    self.data_raw = self.data_raw[self.data_raw.find(b'#')+11:-1]
    return self.data_raw
def get_data(self):
    return frombuffer(self.get_data_raw(),int8)
def get_log_data(self):
    self.log_data = self.dev.query(f"C{self.channel}:INSP? 'WAVEDESC'")
    return self.log_data
def save_data_raw(self,filename,FORCE=False):
    temp_filename = f'{filename}_WAVEMASTERCH{self.channel}'
    if os.path.exists(os.path.join(os.getcwd(),temp_filename)) and
→not (FORCE) :
       print('\nFile ', temp_filename, ' already exists, change filename or_
←remove old file\n')
       return
    f = open(temp_filename, 'wb') # Save data
    f.write(self.data_raw)
    f.close()
def save_log_data(self,filename,FORCE=False):
```

```
(continued from previous page)
```

```
temp_filename = f'{filename}_WAVEMASTERCH{self.channel}.log'
if os.path.exists(os.path.join(os.getcwd(),temp_filename)) and_
onot(FORCE):
    print('\nFile ', temp_filename, ' already exists, change filename or_
oremove old file\n')
    return
f = open(temp_filename,'w')
f.write(self.log_data)
f.close()
```

Those will then be attributes of the class **Channel** and may be called from the class **Driver** (depending on the channel's instance name in this class):

```
self.channel1.get_data()
```

2.2.3 Additional necessary functions/files

Function get_driver_model (in each class but Driver_CONNECTION)

The function get_driver_model should be present in each of the classes of the *<manufacturer>_<MODEL>.py* but the class **Driver_CONNECTION** (including the class Driver and any optionnal class **Module_MODEL**), in order for many features of the package to work properly. It simply consists in a list of predefined elements that will indicate to the package the structure of the driver and predefined variable and actions. There are three possible elements in the function get_driver_model: *Module, Variable* and *Action*.

Shared by the three elements (Module, Variable, Action):

- 'name': nickname for your element (argument type: string)
- 'element': element type, exclusively in: 'module', 'variable', 'action' (argument type: string)
- 'help': quick help, optionnal (argument type: string)

Module:

• 'object' : attribute of the class (argument type: Instance)

Variable:

- 'read': class attribute (argument type: function)
- 'write': class attribute (argument type: function)
- 'type': python type, exclusively in: int, float, bool, str, bytes, np.ndarray, pd.DataFrame
- 'unit': unit of the variable, optionnal (argument type: string)

Caution: Either 'read' or 'write' key, or both of them, must be provided.

Action:

• 'do' : class attribute

Example code:

```
def get_driver_model(self):
    model = []
    model .append({'name':'linel', 'element':'module','object':self.slot1,'help':
    'Simple help for linel module'})
    model .append({'name':'amplitude', 'element':'variable', 'type':float, 'read
    ':self.get_amplitude, 'write':self.set_amplitude, 'unit':'V', 'help':'Simple help_
    for amplitude variable'}
    model.append({'name':'go_home', 'element':'action', 'read':self.home, 'help':
    'Simple help for go_home action'})
return model
```

Driver utilities structure (<manufacturer>_<MODEL>_utilities.py file)

This file should be present in the driver directory (*<manufacturer>_<MODEL>.py*).

Here is a commented example of the file <manufacturer>_<MODEL>_utilities.py, further explained bellow:

```
category = 'Optical source'
                                                       #
class Driver_parser():
   def __init__(self, Instance, name, **kwargs):
       self.name = name
       self.Instance = Instance
   def add_parser_usage(self,message):
       """Usage to be used by the parser"""
       usage = f"""
{message}
 ----- Examples: ------
usage: autolab driver [options] args
   autolab driver -D {self.name} -A GPIB0::2::INSTR -C VISA -a 0.2
   load {self.name} driver using VISA communication protocol with address GPIB....
\rightarrowand set the laser pump current to 200mA.
   autolab driver -D nickname -a 0.2
   Similar to previous one but using the device's nickname as defined in local_
⇔config.ini
           .....
       return usage
   def add_parser_arguments(self,parser):
       """Add arguments to the parser passed as input""" #
       parser.add_argument("-a", "--amplitude", type=str, dest="amplitude", _____
return parser
   def do_something(self,args):
       if args.amplitude:
           # next line equivalent to: self.Instance.amplitude = args.amplitude
           getattr(self.Instance, 'amplitude') (args.amplitude)
```

(continued from previous page)

def ex	<pre>xit(self):</pre>	#
se	elf.Instance.close()	#

It contains:

- The category of the instrument (see autolab.infos (from python shell) or autolab infos for (OS shell) for examples of identified categories).
- A class **Driver_parser** with 5 functions:

1) _____: defines class attributes

2) add_parser_usage: adds help to the parser in oorder to help the user

3) add_parser_arguments: configures options to be used from the OS shell (e.g. autolab driver -D nickname -a 2). See *Command driver* for full usage.

4) do_something: configures action to perform/variable to set (here: modify the amplitude to the the provided argument value), and link them to the values of the argument added with 3).

5) exit: closes properly the connection

Please do consider, keeping each line ending with a # character in the example as is. This way you would need to modify 3 main parts to configure options, associated actions and help: 3), 4) and 2) (respectively).

CHAPTER 3

Devices (High-level interface)

3.1 What is a Device ?

The high-level interface of Autolab is an abstraction layer of its low-level interface, which allows to communicate easily and safely with laboratory instruments without knowing the structure of its associated **Driver**.

In this approach, an instrument is fully described with a hierarchy of three particular **Elements**: the **Modules**, the **Variables** and the **Actions**.

- A Module is an Element that consists in a group of Variables, Actions, and sub-Modules. The top-level Module of an instrument is called a Device.
- A Variable is an Element that refers to a physical quantity, whose the value can be either set and/or read from an instrument (wavelength of an optical source, position of a linear stage, optical power measured with a power meter, spectrum measured with a spectrometer...). Depending on the nature of the physical quantity, it may have a unit.
- An **Action** is an **Element** that refers to a particular operation that can be performed by an instrument. (homing of a linear stage, the zeroing of a power meter, the acquisition of a spectrum with a spectrometer...). An **Action** may have a parameter.

The **Device** of a simple instrument is usually represented by only one **Module**, and a few **Variables** and **Actions** attached to it.

```
-- Tunics (Module/Device)
|-- Wavelength (Variable)
|-- Output state (Variable)
```

Some instruments are a bit more complex, in the sense that they can host several different modules. Their representation in this interface generally consists in one top level **Module** (the frame) and several others sub-**Modules** containing the **Variables** and **Actions** of each associated modules.

```
-- XPS Controller (Module/Device)
|-- ND Filter (Module)
|-- Angle (Variable)
```

(continued from previous page)

```
|-- Transmission (Variable)
|-- Homing (Action)
|-- Linear stage (Module)
|-- Position (Variable)
|-- Homing (Action)
```

This hierarchy of Elements is implemented for each instrument in its drivers files, and is thus ready to use.

3.2 Load and close a Device

The procedure to load a **Device** is the same as for the **Driver**, but with the function get_device. You can provide either the name of a driver with its full configuration, or the name of a local configuration (see local_config).

Note: You can overwrite temporarily some of the parameters values of a configuration by simply providing them as keywords arguments in the get_device function:

To close properly the connection to the instrument, simply call its the function close of the **Device**. This object will not be usable anymore.

>>> lightSource.close()

3.3 Navigation and help in a Device

The navigation in the hierarchy of **Elements** of a given **Device** is based on relative attributes. For instance, to access the **Variable** wavelength of the **Module** (**Device**) my_tunics, simply execute the following command:

>>> lightSource.wavelength

In the case of a more complex **Device**, for instance a power meter named my_power_meter that has several channels, you can access the **Variable** power of the first channel channel1 with the following command:

```
>>> powerMeter = autolab.get_device('my_power_meter')
>>> powerMeter.channel1.power
```

Every **Element** in Autolab is provided with a function help that can be called to obtain some information about it, but also to know which further **Elements** can be accessed through it, in the case of a **Module**. For a **Variable**, it will display its read and/or write functions (from the driver), its python type, and its unit if provided in the driver. For an **Action**, il will display the associated function in the driver, and its parameter (python type and unit) if it has one. You can also print () the object to display this help.

```
>>> lightSource.help()
>>> print(lightSource.wavelength)
>>> powerMeter.help()
>>> print(powerMeter.channel1)
>>> powerMeter.channel1.power.help()
```

3.4 Use a Variable

If a Variable is readable (read function provided in the driver), its current value can be read by calling its attribute:

```
>>> lightSource.wavelength()
1550.55
>>> lightSource.output()
False
```

If a **Variable** is writable (write function provided in the driver), its current value can be set by calling its attribute with the desired value:

```
>>> lightSource.wavelength(1549)
>>> lightSource.output(True)
```

To save locally the value of a readable **Variable**, use its function *save* with the path of the desired output directory (default filename), or file:

```
>>> lightSource.wavelength.save('.\mesures\')
>>> lightSource.wavelength.save('.\mesures\power.txt')
```

3.5 Use an Action

You can execute an **Action** simply by calling its attribute:

```
>>> linearStage = autolab.get_device('my_linear_stage')
>>> linearStage.goHome()
```

3.6 Script example

With all these commands, you can now create your own Python script. Here is an example of a script that sweep the wavelength of a light source, and measure a power of a power meter:

```
# Import the package
import autolab
import pandas as pd
# Open the Devices
myTunics = autolab.get_device('my_tunics')
myPowerMeter = autolab.get_device('my_power_meter')
# Turn on the light source
myTunics.output(True)
# Sweep its wavelength and measure a power with a power meter
df = pd.DataFrame()
for wl in range(1550,1560,0.01) :
# Set the parameter
myTunics.wavelength(wl)
# Measures the values
```

(continued from previous page)

```
wl_measured = myTunics.wavelength()
power = myPowerMeter.line1.power()

# Store the values in a list
    df = df.append({'wl_measured':wl_measured, 'power':power},ignore_index=True)

# Turn off the light source
myTunics.output(False)

# Close the Devices
myTunics.close()
myPowerMeter.close()

# Save data
df.to_csv('data.csv')
```

CHAPTER 4

Local configuration

To avoid having to provide each time the full configuration of an instrument (connection type, address, port, slots, \dots) to load a **Driver** or a **Device**, Autolab proposes to store it locally for further use.

More precisely, this configuration is stored in a local configuration file named local_config.ini, which is located in the local directory of Autolab. Both this directory and this file are created automatically in your home directory the first time you use the package (the following messages will be displayed, indicating their exact paths).

INFORMATION: The local folder AUTOLAB has been created : C:\Users\<USER>\autolab INFORMATION: The configuration file local_config.ini has been created : C:\Users\ \rightarrow <USER>\autolab\local_config.ini

Warning: Do not move or rename the local directory nor the configuration file.

A local configuration is composed of several parameters:

- The name of the local configuration, which is usually the nickname of your instrument in Autolab.
- The name of the associated Autolab driver.
- All the connection parameters (connection, address, port, slots, ...)

To see the list of the available local configurations, call the function <code>list_local_configs</code>.

>>> autolab.list_local_configs()

To know what parameters have to be provided for a particular **Driver** or **Device**, use the function *config_help* with the name of corresponding driver.

>>> autolab.config_help('yenista_TUNICS')

This section describes the procedure to create or modify a local configuration either through Autolab, or by editing directly the configuration file on your computer.

4.1 Python commands

The first way to create or modify a local configuration is to use the dedicated functions in Autolab. To create a new local configuration, call the function set_local_config with the configuration name, the driver name, and the parameters with their values. (Note that driver and connection keywords are mandatory).

The function set_local_config can also be used to update an existing local configuration. As above, provide configuration name followed by the parameters and values you want to update, with the additional keyword modify=True to confirm the local changes. Any parameter can be changed in this way.

>>> autolab.set_local_config('my_tunics', address='GPIB0::4::INSTR')

You can display the content of a local configuration by calling the function show_local_config with the name of the local configuration.

```
>>> autolab.show_local_config('my_tunics')
```

Finally, to remove a parameter from a local configuration, call the function remove_local_config_parameter with the configuration name and the name of the parameter to remove.

```
>>> autolab.set_driver_driver('my_tunics', fake_parameter=8)
>>> autolab.remove_local_config_parameter('my_tunics', 'fake_parameter')
```

If you want to remove completely a local configuration, call the function remove_local_config with the name of the configuration to remove.

```
>>> autolab.remove_local_config('my_tunics')
```

******To sum up, you can either provide the full configuration of an instrument in the function ****** get_driver ****** or ****** get_device ******, or save it locally with a nickname, and just provide that nickname in the two previous functions.

4.2 Edit the configuration file

You can also edit directly the local configuration file local_config.ini.

This file is structured in blocks, each of them containing the configuration of an instrument. Each block contains a header (the configuration name / nickname of the instrument in square brackets []). The parameters and values are then listed below line by line, separated by an equal sign =.

```
[<NICKNAME_OF_YOUR_DEVICE>]
driver = <DRIVER_NAME>
connection = <CONNECTION_TYPE>
address = <ADDRESS>
slot1 = <MODULE_NAME>
slot1_name = <MY_MODULE_NAME>
```

To see a concrete example of the block you have to append in the configuration file for a given driver, call the function config_help with the name of the driver. You can then directly copy and paste this exemple into the configuration file, and customize the value of the parameters to suit those of your instrument. Here is an example for the Yenista Tunics light source:

```
[my_tunics]
driver = yenista_TUNICS
connection = VISA
address = GPIB0::2::INSTR
```

Save the configuration file, and go back to Autolab. You don't need to restart Autolab, the configuration file will be read automatically at the next request.

```
>>> laserSource = autolab.get_driver('my_tunics')
>>> laserSource = autolab.get_device('my_tunics')
```

CHAPTER 5

Graphical User Interface (GUI)

Autolab is provided with a user-friendly graphical interface based on the **Device** interface, that allows the user to interact even more easily with its instruments. It can be used only for local configurations (see local_config).

The GUI has three panels : a **Control Panel** that allows to see visually the architecture of a **Device**, and to interact with an instrument through the *Variables* and *Actions*. The **Monitoring Panel** allows the user to monitor a *Variable* in time. The **Scanning Panel** allows the user to configure the scan of a parameter and the execution of a custom recipe for each value of the parameter.

To start the GUI from a Python shell, call the function gui of the package:

```
>>> import autolab
>>> autolab.gui()
```

To start the GUI from an OS shell, call:

```
>>> autolab gui
```

5.1 Control panel

The Autolab GUI Control Panel provides an easy way to control your instruments. From it, you can visualize and set the value of its *Variables*, and execute its *Action* through graphical widgets.

AUTOLAB - Control Panel				_	\times
Open scanner Report bugs / sugge	stions Help				
Objects	Туре	Actions	Values		-
✓ winspec	Module				
exposureTime (s)	Variable	Read			- 1
autoExposureTime	Variable	Read			
autoBackgroundRemoval	Variable	Read			
spectrum	Variable			_	
temperature (°C)	Variable	Read			
mainPeakWavelength (nm)	Variable	Read]		
mainPeakFWHM (nm)	Variable	Read]		
maxPower	Variable	Read			
integratedPower	Variable	Read	5.0586e+06		
acquire	Action	Execute		_	
✓ xps	Module	-	-		
NSR1_TOC	Module				
velocity	Variable	Read			
acceleration	Variable	Read			
angle	Variable	Read			
transmission	Variable	Read	0.0701798		
setMin	Action	Everute			

Fig. 1: Control panel

AUTOLAB - Control Panel				_	\times
Open scanner Report bugs / sugge	stions Help				
Objects	Туре	Actions	Values		-
 winspec 	Module				
exposureTime (s)	Variable	Read			- 1
autoExposureTime	Variable	Read			
autoBackgroundRemoval	Variable	Read			
spectrum	Variable				
temperature (°C)	Variable	Read			
mainPeakWavelength (nm)	Variable	Read			
mainPeakFWHM (nm)	Variable	Read	1		
maxPower	Variable	Read	1		
integratedPower	Variable	Read	5.0586e+06		
acquire	Action	Execute		-	
✓ xps	Module				
NSR1_TOC	Module				
velocity	Variable	Read			
acceleration	Variable	Read			
angle	Variable	Read			
transmission	Variable	Read	0.0701798		
setMin	Action	Evecute			

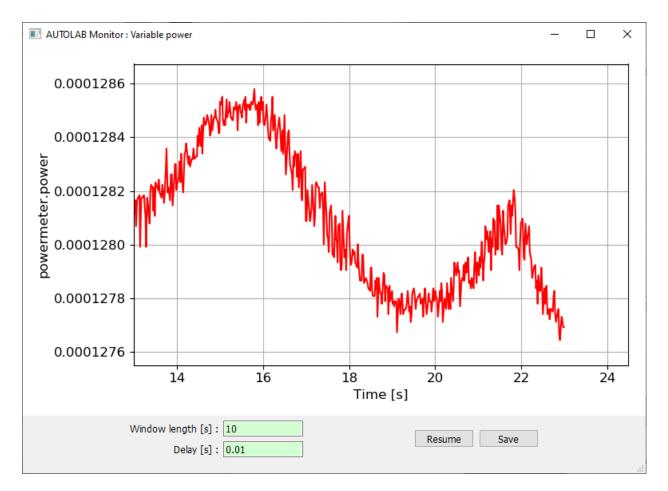


Fig. 2: Monitoring panel

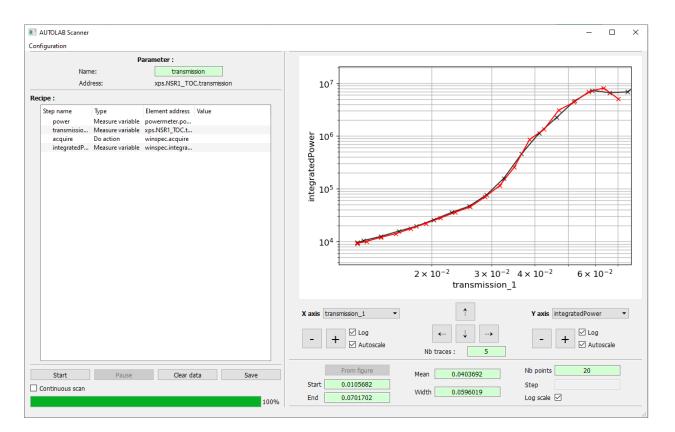


Fig. 3: Scanning panel

5.1.1 Devices tree

By default, the name of each local configuration in represented in a tree widget. Click on one of them to load the associated **Device**. Then, the corresponding *Element* hierarchy appears.

The help of a given **Element** (see *Devices (High-level interface)*) can be displayed though a tooltip by passing the mouse over it (if provided in the driver files).

Actions

A button **Execute** is present in each *Action* line. Clicking the button executes the associated action. If the *Action* has a parameter, fill its value in the associated widget.

Variables

The value of a Variable can be set or read if its type is numerical (integer, float or boolean).

If the *Variable* is readable (read function provided in the driver), a **Read** button is available on its line. When clicking on this button, the *Variable*'s value is read and displayed in a line edit widget (integer / float values) or in a checkbox (boolean).

If the *Variable* is writable (write function provided in the driver), its value can be edited and sent to the instrument (return pressed for interger / float values, check box checked or unchecked for boolean values). If the *Variable* is also readable, a **Read** operation will be executed automatically after that.

To read and save the value of a *Variable*, right click on its line and select **Read and save as...** You will be prompted to select the path of the output file.

The colored displayed at the end of a line corresponds to the state of the displayed value:

- The orange color means that the currently displayed value is not necessary the current value of the **Variable** in the instrument. The user should click the **Read** button to update the value in the interface.
- The green color means that the currently displayed value is up to date (except if the user modified its value directly on the instrument. In that case, click the **Read** button to update the value in the interface).

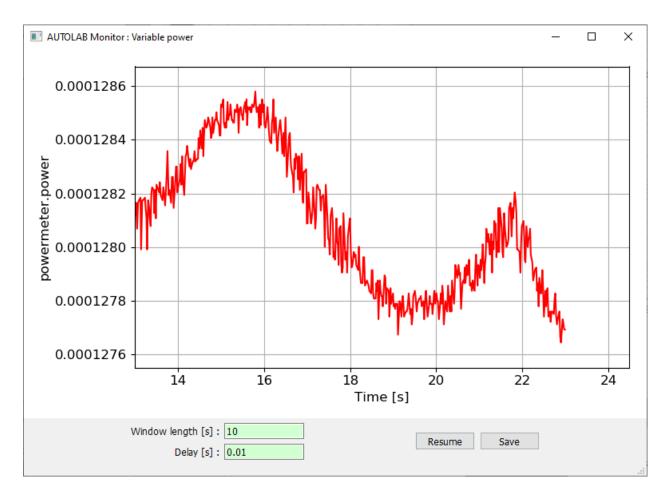
5.1.2 Monitoring

A readable and numerical *Variable* can be monitored in time. To start the monitoring of this *Variable*, right click on it and select **Start monitoring**. Please visit the section *Monitoring*.

5.1.3 Scanning

You can open the scanning interface with the associated button in the menu bar of the control panel window. To configure a scan, please visit the section *Scanning*.

5.2 Monitoring



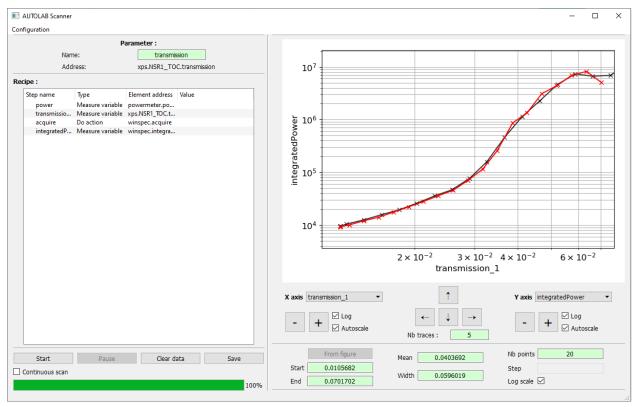
The Autolab GUI Monitoring allows you to monitor a *Variable* in time. To start a monitoring, right click on the desired *Variable* in the control panel, and click **Start monitoring**. This *Variable* has be be readable (read function provided in the driver) and numerical (integer or float value).

In the Monitoring window, you can set the **Window length** in seconds. Any points older than this value is removed. You can also set a **Delay** in seconds, which corresponds to a sleep delay between each measure.

You can pause the monitoring with the **Pause** button, and save the current graph and data with the **Save** button. You will be prompted to give a folder path where the data will be saved.

5.3 Scanning

The Autolab GUI Scanning interface allows the user to sweep a parameter over a certain range of values, and execute for each of them a custom recipe.



5.3.1 Scan configuration

Parameter

The first step to do is to configure the scan parameter. The parameter is a *Variable* which is writable (write function provided in the driver) and numerical (integer or float value). To set a *Variable* as scan parameter, right click on it on the control panel window, and select **Set as scan parameter**.

The user can change the name of the parameter with the line edit widget. This name will be used is the data files.

Parameter range

The second step is to configure the range of the values that will be applied to the parameter during the scan. The user can set the start value, the end value, the mean value, the range width, the number of points of the scan or the step between two values. The user can also space the points following a log scale by checking the **Log** check box.

Recipe

The third step is to configure the recipe, that will be executed for each value of the parameter. There are three kinds of recipe steps:

- Measure the value of a Variable. Right click on the desired *Variable* in the control panel and select Measure in scan recipe to append this step to the recipe.
- Set the value of a Variable. Right click on the desired *Variable* in the control panel and select Set value in scan recipe to append this step to the recipe. The variable must be numerical (integer, float or boolean value). To set the value, right click on the recipe step and click Set value. The user can also directly double click on the value to change it.
- Execute an Action. Right click on the desired *Action* in the control panel and select **Do in scan recipe** to append this step to the recipe.

Each recipe step must have a unique name. To change the name of a recipe step, right click on it and select **Rename**, or directly double click on the name to change it. This name will be used in the data files.

The recipe steps can be dragged and dropped to modify their relative order. They can also be removed from the recipe using the right click menu **Remove**.

Store the configuration

Once the configuration of a scan is finished, the user can save it locally in a file for future use, by opening the menu **Configuration** and selecting **Export current configuration**. The user will be prompted for a file path in which the current scan configuration (parameter, parameter range, recipe) will be saved.

To load a previously exported scan configuration, open the menu **Configuration** and select **Import configuration**. The user will be prompted for the path of the configuration file.

5.3.2 Scan execution

- **Start** button: start / stop the scan.
- Pause button: pause / resume the scan.
- **Continuous scan** check box: if checked, start automatically a new scan when the previous one is finished. The state of this check box can be changed at any time.
- Clear data button: delete any previous datapoint recorded.
- Save button: save the data of the last scan. The user will be prompted for a folder path, that will be used to save the data and a screenshot of the figure.

Note: The scan configuration cannot be modified or loaded when a scan is started. Stop it first.

Note: During a scan, the background color of each item (parameter or recipe step) indicates its current state. An orange item is being processed, a green one is finished.

5.3.3 Figure

The user can interact with the figure at any time (during a scan or not).

To zoom/unzoom the current view of the figure, use the buttons **Zoom** and **Unzoom** of each axis, or use the scroll wheel of the mouse. To move the current view of the figure, use the buttons **Left**, **Right**, **Up** and **Down**, or hold and drag the figure directly with the mouse.

After that a first loop of the scan has been processed, the user can select the **Variable** displayed in x and y axis of the figure. If the *Variable* of the x axis is the parameter, the user can use the button **From figure** to set the current x axis range of the figure, as the new parameter range.

Finally, the user can keep the previous curves of a scan by setting the **Traces** number.

OS shell

Most of the Autolab functions can also be used directly from a **Windows** or **Linux** terminal without opening explicitely a Python shell.

Just execute the command autolab or autolab -h or autolab --help in your terminal to see the available subcommands.

C:\Users\qchat> autolab C:\Users\qchat> autolab -h Hostname:/home/User\$ autolab --help

The subcommands are :

- autolab infos: a shortcut of the python function autolab.infos() to list the drivers and the local configurations available on your system.
- autolab gui: a shortcut of the python function autolab.gui() to start the graphical interface of Autolab.
- autolab device : a shortcut of the python interface Device (see *Command device*)
- autolab driver: a shortcut of the python interface Driver (see *Command driver*)
- autolab doc: a shortcut of the python function autolab.doc() to open the present online documentation.
- autolab report : a shortcut of the python function autolab.report() to open the present online documentation.
- autolab stats: a shortcut to manage (enable/disable/query) the anonymous data would collect at import autolab. No personal data is sent, sha256 hashing is used to generate and send a single ID once. Those are used for statistics.

Table of contents: The two sections that follow are equivalent for the commands autolab driver and autolab device (unless specified). They will guide you through getting basic help and minimal formatting of command lines (minimal arguments to pass) to instantiate your instrument (set up the connection with it, etc.).

6.1 Getting help

Three helps are configured (device or driver may be used equally in the lines bellow):

1) Basic help of the commands autolab driver/device:

>>> autolab driver -h

It including arguments and options formatting, definition of the available options and associated help and informations to retrieve the list of available drivers and local configurations (command: autolab infos).

2) Basic help about the particular name driver/device you provided:

>>> autolab driver -h -D driver_name

It includes the category of the driver/device (e.g. Function generator, Oscilloscope, etc.), a list of the implemented connections (-C option), personnalized usage example (automatically generated from the driver.py file), and examples to use and set up a local configuration using command lines (see *Local configuration* for more informations about local configurations).

3) Full help message about the driver/device:

>>> autolab driver -D driver_name -C connection -A address -h
>>> autolab driver -D nickname -h

For driver:

It includes the list of the implemented connections (-C option), the list of the available additional modules (classes **Channel**, **Trace**, **Module_MODEL**, etc.; see *Write your own Driver*), the list of all the methods that are instantiated with the driver (for direct use with the command: autolab driver; see *Command driver*), and an extensive help for the usage of the pre-defined options.

For device:

It includes the hierarchy of the device and all the defined *Modules*, *Variables* and *Actions* (see *Function get_driver_model (in each class but Driver_CONNECTION)* and *Command device* for more informations on the definition and usage respectively).

Note that this help requires the instantiation of your instrument to be done, in other words it requires valid arguments for options -D, -C and -A (that you can get for previous helps) and a working physical link.

6.2 Instantiate a driver

The commands autolab driver/device will set up a connection to your instrument, perform the requested operation(s), and finally close properly the connection. To **set up the connection** you need to give valid arguments as requested by the driver (build to suit the physical instrument requirements).

A typical command line structure is:

To set up the connection for the first time, we recommand to follow the different help states (see _name_shell_help), that usually guide you through filling the arguments corresponding to the above options. To use one of Autolab's

driver to drive an instrument you need to provide its name. This is done with the option -D. -D option accepts either a driver_name (e.g. agilent_33220A, etc) or a config_name (nickname as defined in your local_config.ini, e.g. my_agilent). A full list of the available driver names and config names may be found using the command autolab infos. Due to Autolab's drivers structure you also need to provide a -C option for the connection type (corresponding to a class to use for the communication, see *Write your own Driver* for more informations) when instantiating your device. The available connection types (arguments for -C option) are driver dependent (you need to provide a valid -D option) and may be access with a second stage help (see *Getting help*). Lately you will need to provide additional options/arguments to set up the communication. One of the most common is the address for which we cannot help much. At this stage you need to make sure of the instrument address/set the address (on the physical instrument) and format it the way that the connection type is expecting it (e.g. for an ethernet connection with address 192.168.0.1 using VISA connection type: TCPIP::192.168.0.1::INSTR). You will find in the second stage help automatically generated example of a minimal command line (as defined in the driver) that should be able to instantiate your instrument (providing you modify arguments to fit your conditions).

Other arguments may be necessary for the driver to work properly. In particular, additional connection argument may be passed through the option -O, such as the port number (for SOCKET connection type), the gpib board index (for GPIB connection) or the path to the dll library (for DLL connection type). In addition, for *complex* instruments (such as instruments with 'slots'), this options provides you with a reliable way to indicate the physical configuration of your instrument [e.g. Module_TEST111 is physically inserted in slot 1, Module_TEST222 is physically inserted in slot 5 (-O slot1=Module_TEST111 slot5=Module_TEST222); see :ref:'' for more informations].

6.3 Command driver

See *Instantiate a driver* for more informations about the connection. Once your driver is instantiated you will be able to perform **pre-configured operations** (see *Driver utilities structure (<manufacturer>_<MODEL>_utilities.py file)* for how to configure operations) as well as **raw operations** (-m option). We will discuss both of them here as well as a quick (bash) **scripting example**. In the rest of this sections we will assume that you have a working local configuration for your instrument with a nickname my_instrument.

6.3.1 Usage of pre-configured operations

You may access an extensive driver help, that will particularly list the pre-defined options, using:

>>> autolab driver -D my_instrument -h

It includes the list of the implemented connections, the list of the available additional modules (classes **Channel**, **Trace**, **Module_MODEL**, etc.; see *Write your own Driver*), the list of all the methods that are instantiated with the driver (for direct use with the command: autolab driver; see *Command driver*), and an extensive help for the usage of the pre-defined options. For instance if an option -a has been defined in the file driver_utilities.py (see *Driver utilities structure (<manufacturer>_<MODEL>_utilities.py file)*), one may use it to perform the associated action, say to modify the amplitude, this way:

>>> autolab driver -D my_instrument -a 2

This modifies the amplitude to 2 Volts (if the unit is set to Volt).

In addition, if the instrument has several channels, an channel option is most likely implemented and one can modify the amplitude of channel 4 and 6 to 2 Volts using:

>>> autolab driver -D my_instrument -a 2 -c 4,6

Warning: No space must be present within an argument or option (e.g. do not write -c or -c 4, 6).

Furthermore, several operations may be perform in a single and compact script line. One can modify the amplitude of channel 4 and 6 to 2 Volts and the frequencies (of the same channel) to 50 Hz using:

>>> autolab driver -D my_instrument -a 2 -c 4,6 -f 50

Note: The arguments are non-positional, which means that the previous line is formally equivalent to:

```
>>> autolab driver -D my_instrument -c 4,6 -f 50 -a 2
>>> autolab driver -D my_instrument -f 50 -a 2 -c 4,6
```

6.3.2 Raw operations (-m option)

Independently of the user definition of options in the file driver_utilities.py, you may access any methods that are instantiated with the driver using the -m option.

Important: This is not a *safe* environment, but it allows you to access all the functionnalities of a driver and doesn't rely on a user configuration.

You may access the **full list of instantiated methods** along with their argument definition, using:

>>> autolab driver -D my_instrument -h

This allow you to simply copy and paste the method you want to use from the list into the following command, directly as *python code*:

```
>>> autolab driver -D my_instrument -m 'get_amplitude()'
>>> autolab driver -D my_instrument -m 'set_amplitude(value)'
```

One may also call several methods separated with a space after -m option:

Note:

1) If strings are passed as arguments, mind the usage of ' and ".

2) It is possible to combine pre-defined options and -m option in a single script line.

6.3.3 Script example

One may stack in a single file several script line in order to perform custom measurement (modify several control parameters, etc.). This is a bash counterpart to the python scripting example provided there *Script example*.

```
#!/bin/bash
                               # Very first line of the file (this is bash code)
i=1
                               # Definition of a variable
for volts in $(seq 0 0.1 5)
                               # Definition of a loop (variable volts goes from 0 to 5.
\rightarrow with steps of 0.1)
do
echo $volts
                               # Print the value of the volts variable
autolab driver -D my_function_generator -a $volts # Increase the amplitude of my_
→function_generator
autolab driver -D my_oscilloscope -c 1,2,4 -o $i
                                                    # Get channels 1, 2 and 4 from my_
\rightarrowoscilloscope and save the according files with a name starting with the number of
\rightarrow iteration of the loop (i)
i=$(($i+1))
                               # Increment i variable of 1 at each loop iteration
                               # End of the for loop
done
```

Note:

- 1) Any time the command autolab driver is called it sets up the connection. It is then inherently slightly slower (instrument dependant for the amount of time that usually range from 0.1 to 0.5 seconds) than scripting in python.
- 2) The whole script looks sightly simpler and shorter than its python counterpart.

6.4 Command device

To read, write or save the value of a Variable, or to execute an Action, use the command autolab device in your terminal with the following general format:

autolab device -D <DRIVER_NAME or CONFIG_NAME> -e <ELEMENT_ADDRESS> <OPTIONS>

The **Element address** indicates the address of the desired **Variable** or **Action** in the Autolab Device hierarchy, using a point separator. This command will establish a connection to your instrument, perform the requested operation, and finally close properly the connection. See *Instantiate a driver* for more informations about the connection.

The available operations are listed below:

• **To read and print** the value of a readable **Variable** in the terminal, provide its address without any other options:

```
>>> autolab device -D myTunics -e wavelength 1550.00
```

• To read and save the value of a readable Variable in a file, provide its address with the option -p or --path with the desired output file or folder path:

```
>>> autolab device -D myPowerMeter -e line1.power -p .\data\power.txt
```

• To set the value of a writable Variable, provide its address and the option -v or --value with the desired value:

>>> autolab device -D myTunics -e wavelength -v 1551

• To execute an Action, provide its address without any options (or with the option -v or --value with the desired value if the Action has a parameter):

>>> autolab device -D myLinearStage -e goHome

• To display the help of any Element, provide its address with the option -h or --help :

```
>>> autolab device -D myLinearStage -e goHome -h
```

Doc / Reports / Stats

7.1 Documentation

You can open directly this documentation from Python by calling the function doc of the package:

>>> autolab.doc()

>>> autolab doc

7.2 Bugs & suggestions reports

If you encounter some problems or bugs, or if you have any suggestion to improve this package, or one of its driver, please open an Issue on the GitHub page of this project https://github.com/qcha41/autolab/issues/new

You can also directly call the function report of the package, which will open this page in your web browser:

```
>>> autolab.report()
>>> autolab report
```

Alternatively, you can send an email to the authors (see About).

7.3 Statistics of use

At startup, Autolab is configured to send only once a completely anonymous signal (sha256 hashed ID) over internet for statistics of use. This helps the authors to have a better understanding of how the package is used worldwide. No personal data is transmitted during this process. Also, this is done in background, with no impact on the performance of Autolab. You can manage the state of this feature in Autolab through these functions:

```
>>> autolab.set_stats_enabled(True/False)
>>> state = autolab.is_stats_enabled()
```

```
>>> autolab stats -e/-d
>>> autolab stats -q
```

Releases notes

8.1 Development version

- The help of an Element (Device approach) can be either displayed through its element.help() function or by printing the object print (element).
- The help of a Variable (Device approach) now display its python type.

8.2 (last) v1.1.10:

- sacher_PC500: addition of the connection class Driver_GPIB
- v1.1.9: * sacher_PC500: minor modifications
- v1.1.8: * sacher_PC500: minor modifications
- v1.1.7: * sacher_PC500: minor modifications
- v1.1.6: * Addition of the driver sacher_PC500
- v1.1.5: * yokogawa_AQ6370: fix on the single function of the class Driver: it will now wait to finish the operation

v1.1.4: * yokogawa_AQ6370: small fixes including modification of the names of communication functions (send and recv became write and read respectively)

v1.1.3: * minor fixes * addition of a few functions and the connection class Driver_GPIB to agilent_33220A * addition of the driver keithley_2200

- v1.1.2: fixed issue with using local config and OS command autolab driver
- v1.1.1: fixed installation issue regarding version.txt

8.3 v1.1

Core:

- autolab.help() renamed in autolab.doc()
- Functions get_driver_by_config and get_device_by_config have been deleted. Use get_driver or get_device functions to load an instrument either with its full configuration or with a local configuration.
- The methods of a Driver instance can be listed through the function autolab.explore_driver(instance).
- New function autolab.infos() that displays the available drivers and local configurations in the system.
- The local configurations are now refered as 'local_config' in the functions of autolab.
- The OS shell interface has been completely restructured. Most of the features of Autolab are now available (doc, report, infos, drivers, devices, gui..) through a unique command 'autolab'.
- Added trigger for statistics of use (can be disabled).

Drivers:

- The driver category is now stored in the script <driver>_utilities.py in the same folder (previously <driver>_parser.py).
- exfo_PM1613: 1) Driver update taking into account that the power meter returns * when changing its scale. 2) typos in the type of power of get_driver_model (str -> float).
- Modification of the way we pass argument to socket.send function. Safer now as we explicitly convert the argument to a string (impacted a few instruments that use socket module such as yokogawa_AQ6370, etc.).

Help:

• Efforts to merge all the helps [in python, OS (autolab driver/device), etc.] to a common standard, using the very same functions.

8.4 v1.0

• First push

About

This Python package has been created in 2019 by Quentin Chateiller (PhD student) and Bruno Garbin (post-doc researcher) from the ToniQ team of the C2N-CNRS laboratory (Center for Nanosciences and Nanotechnologies, Palaiseau, France).

The first developpements of the core, the GUI, and the drivers started initially in 2017 by Quentin. Bruno arrived in the team in 2019, providing a new set of Python drivers from its previous laboratory. In order to propose a Python alternative for the automation of scientific experiments in our research team, we finally merged our works in a Python package based on a standardized and robust driver architecture, that makes drivers easy to use and to write by the community.

Thanks to Maxime, Giuseppe and Guilhem for their contributions.

You find this package useful? We would be really grateful if you could help us to improve its visibility ! You can:

- Add a star on the GitHub page of this project
- Spread the word around you
- Mention this package in your research publications

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